

EEE314

Automatic Control Systems

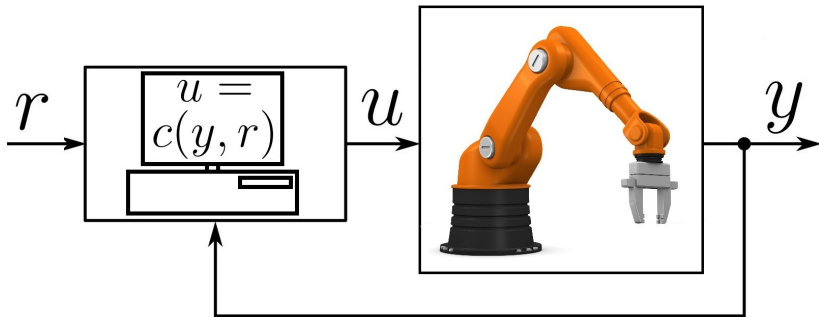
T.C. Trakya University
Faculty of Engineering
Department of Electrical and Electronics Engineering
Control Section

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sirmatel.github.io

Course info - Intro

automatic control:

engineering of dynamical system operation
under uncertainty via feedback



Course info - Course webpage

everything related to the
course is here:

sirmatel.github.io/teaching/314

Dersin internet sayfası

ders ile ilgili her şey burada:

sirmatel.github.io/teaching/314

Course info - Syllabus

all course info is here:

syllabus

check weekly for
announcements

Ders uygulama belgesi

bütün ders bilgileri burada:

ders uygulama belgesi

duyurular için her hafta bakın

Automatic control - Definition

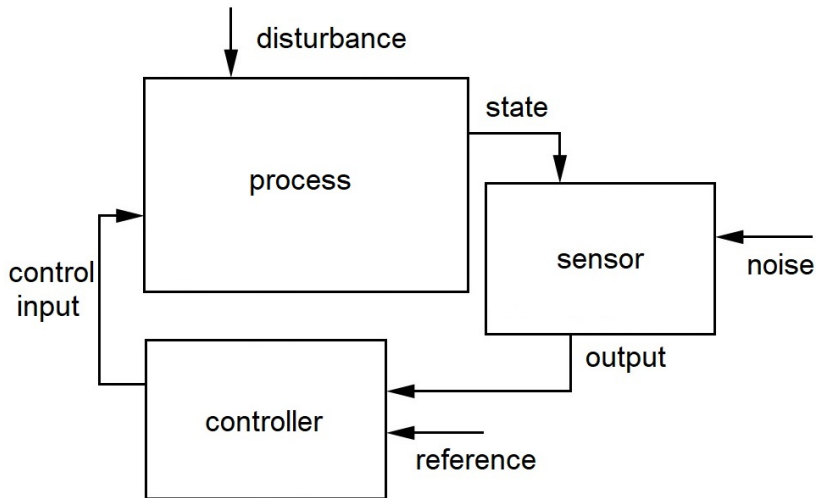


centrifugal governor (18. c.)

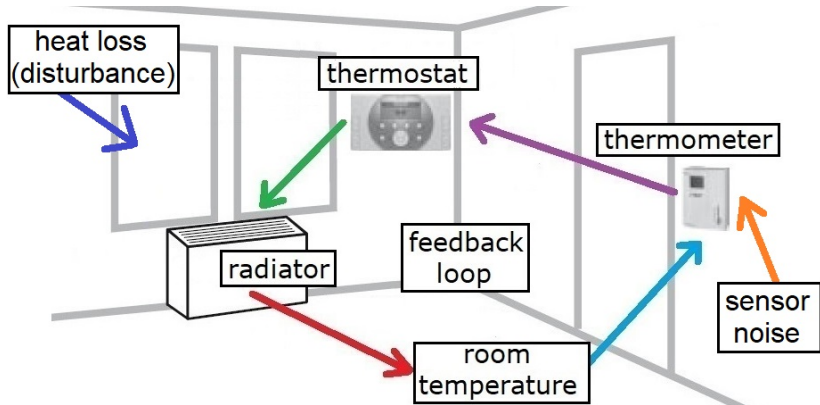
Source: [Mirko Junge](#), CC BY 3.0

Automatic control is a field of engineering/applied mathematics, dealing with the analysis and design of **feedback** mechanisms which enable **dynamical systems** to **behave** approximately as desired without human intervention (and alleviate, to a certain extent, the effect of **uncertainties** that can disrupt this behaviour).

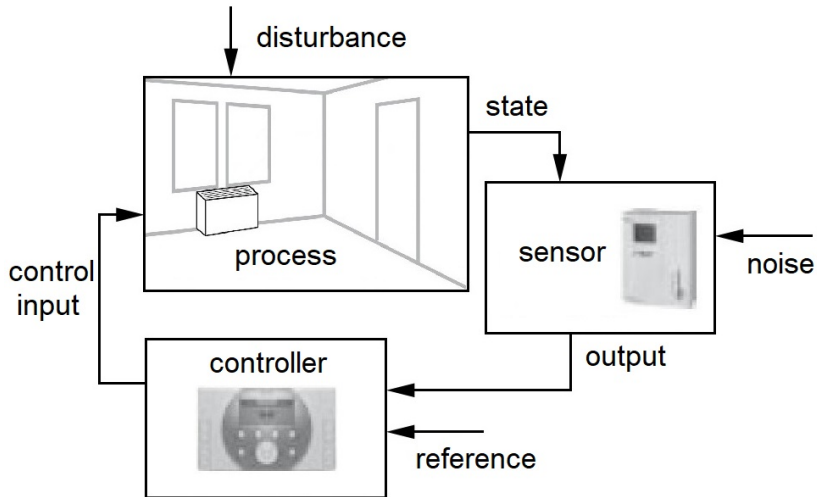
Structure of an automatic control system



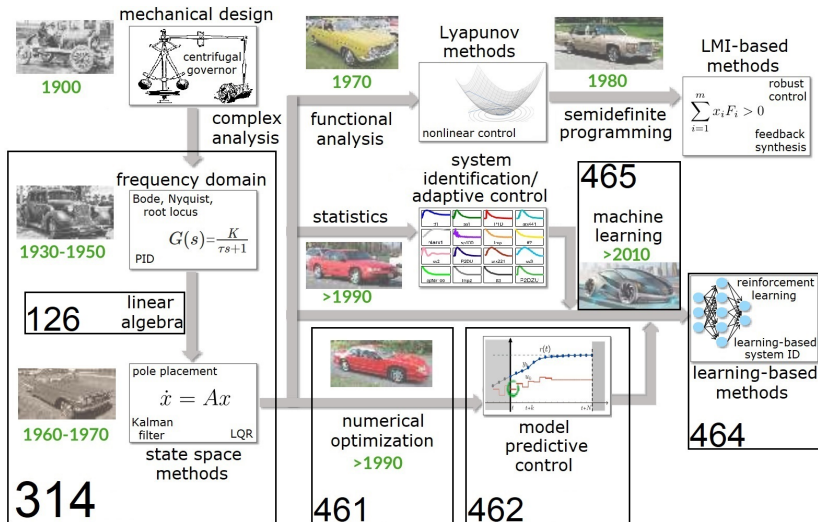
Example: Room temperature control



Example: Room temperature control



Short history of automatic control



Source: Alberto Bemporad, [Machine Learning: A New ICE \(Identification, Control, Estimation\) Age?](#) (adapted)

The Map of Control Theory

Central Hub: continuous, discrete, time, frequency

Predictive: model predictive control, robust mpc, fuzzy control, intelligent

Optimal: hamilton-jacobi-bellman equation, lqr, optimal

Adaptive: model reference adaptive, extremum-seeking, iterative learning control

Robust: mu synthesis, hinfinity

Nonlinear: backstepping, gain scheduling, bang-bang, sliding mode, performance, nyquist, passivity, root locus, phase plane, pole-zero plot, lyapunov stability, nichols chart

Linear: pid, lead-lag, full state feedback, control methods

State Estimation: kalman filter, particle, sigma-point, sensor fusion, tracking, moving horizon estimation, filtering, mapping, observer

Modeling & Simulation: linear state space, nonlinear state space, hybrid system, transfer functions, block diagrams, system id, minimum realizations, first principles

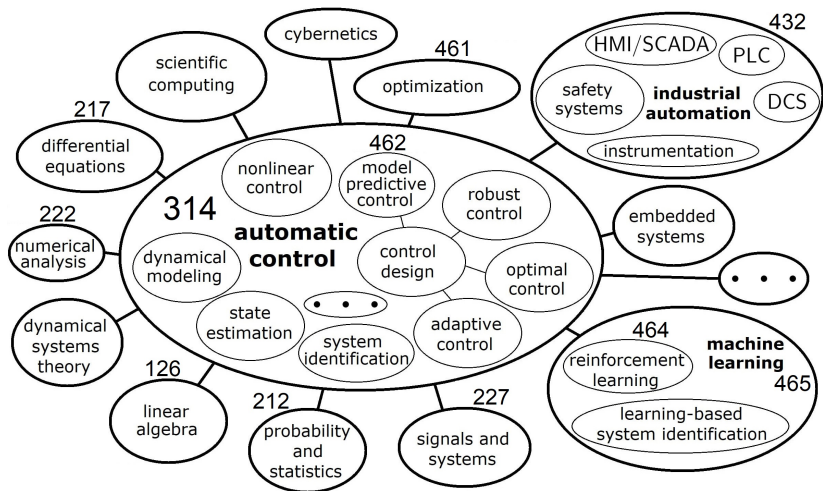
Multi-Agent: leader-follower, swarm, graph theoretic control

brian douglas © aug 2020
 ME-EngineeringMedia

Aspects of control systems projects

- 1) dynamical modeling:** describing system behavior with a mathematical model (usually differential equations)
- 2) system analysis:** examining theoretical features of the system (e.g., stability, controllability etc.) using the model
- 3) simulation:** computing trajectories describing system behavior using the model
- 4) system identification:** estimating the model or its parameters using system measurements
- 5) model validation:** testing validity of the model and its parameters using system measurements
- 6) state estimation design:** designing mechanisms that can estimate system states using the model and system measurements
- 7) control design:** designing feedback mechanisms for shaping system operation under uncertainty using the model and system measurements

Automatic control and related fields



Examples of control applications

**autonomous
vehicles**



**active noise
cancellation**



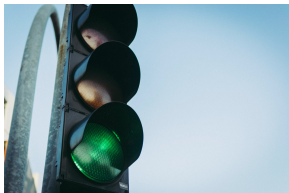
**infrastructure
networks**



robots









**transportation
systems**



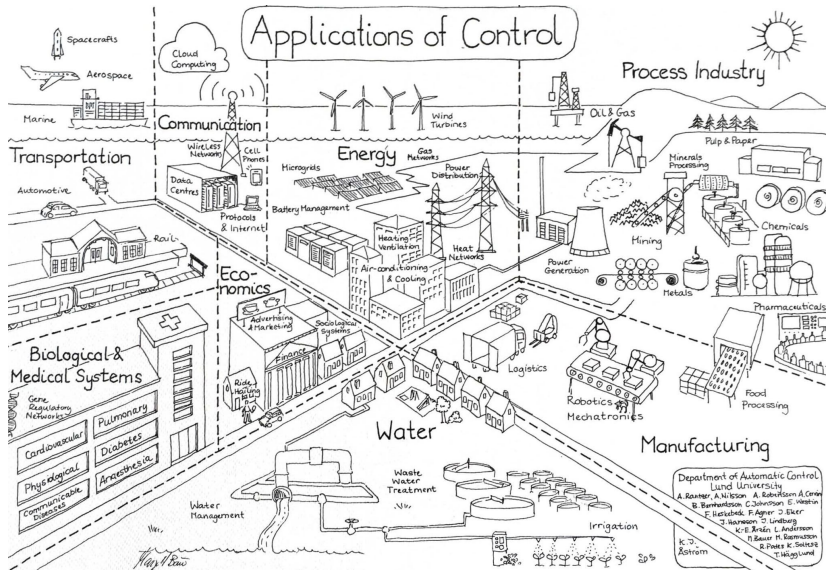
chemical plants



Engineering/mathematics matrix

		fields of applied mathematics					
		differential equations	probability and statistics	automatic control	optimization	machine learning	...
fields of engineering	civil						
	mechanical						
	electrical						
	chemical						
	electronics						
	mechatronics						
	⋮						

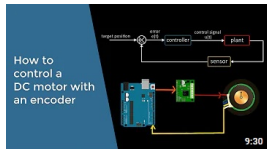
Map of control applications



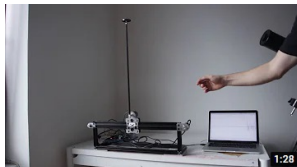
Source: Department of Automatic Control, Lund University, Sweden

Some standard control experiments

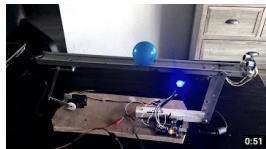
DC motor



inverted pendulum



ball and beam



fan and plate



ball and plate



four tanks system

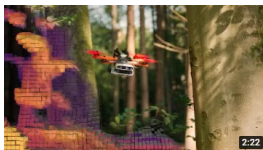


Some advanced control applications

humanoid robot



quadrotor



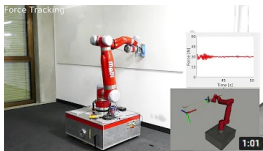
quadruped robot



autonomous race car



mobile industrial robot

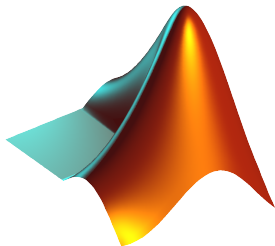


kite and generator

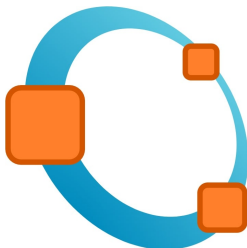


Programming (numerical computing)

MATLAB®



GNU Octave



Kaynak: John W. Eaton

Python



Scilab



Julia



SageMath



Kaynak: The Sage team

Resources

see under resources at:

sirmatel.github.io/teaching/314

for lecture slides, lecture videos, textbooks, exam questions with solutions etc.

Recommended resources on control

- ▶ **Textbook:** *Feedback Systems: An Introduction for Scientists and Engineers*. K. J. Åström and R. M. Murray
- ▶ **Exam questions with solutions:** *Automatic Control 1&2* (exercise collection - past written examinations). Alberto Bemporad
- ▶ **Repository:** *Resourcium* (website with links to resources and structured content on control and automation)
- ▶ **Programming tutorials:** *Control Tutorials for MATLAB® and Simulink®* (website with tutorial examples on control systems with codes and explanations)
- ▶ **Short lectures:** *Steve Brunton* (channel with videos on control systems and related topics)
- ▶ **Virtual control laboratory:** *Control Challenges* (website with animated virtual control experiments/games)

General professional advice

those who know the following topics very well (and also have adequate expertise about the sector they are working in) can work successfully (now, and in the future) in any country and in any (especially **STEM** related) line of work:

- ▶ **English**
- ▶ **engineering math/applied math** (linear algebra, probability and statistics, multivariable calculus, numerical methods, optimization, . . .)
- ▶ **computer science**

Websites (general)

- ▶ learning English: Duolingo, Memrise, Busuu, ...
- ▶ open courses: MIT OpenCourseWare, Stanford Engineering Everywhere, MERLOT, ...
- ▶ open-access textbooks: LibreTexts Commons
- ▶ computer science: CS50 Introduction to Computer Science (Harvard)
- ▶ programming/numerical computing: Python/SciPy, GNU Octave, MATLAB, Scilab, Julia, SageMath, ...